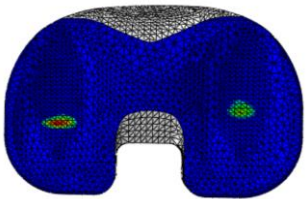
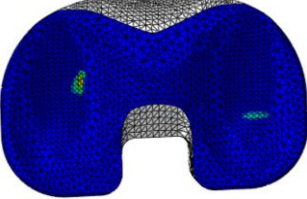
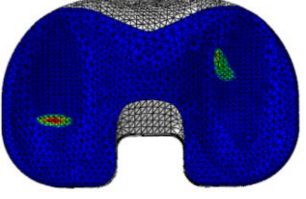
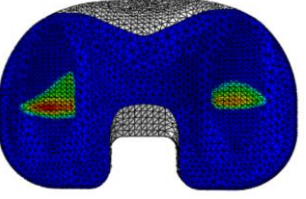
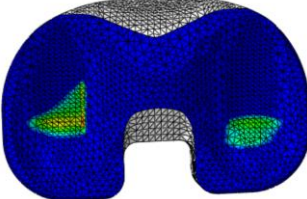
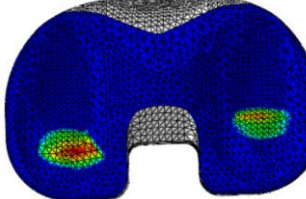
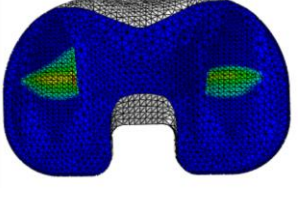
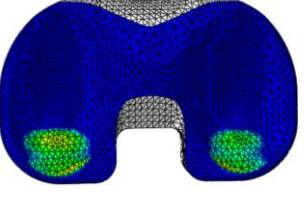
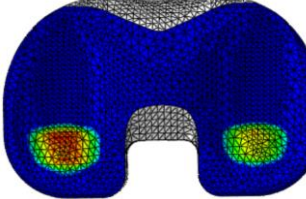
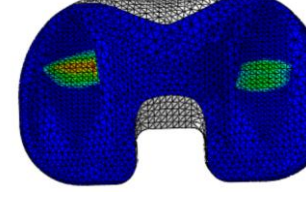
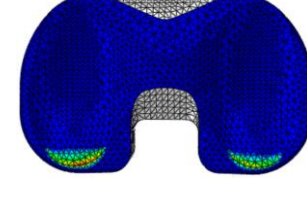
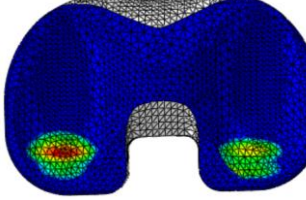
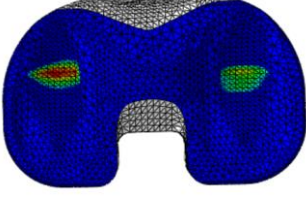
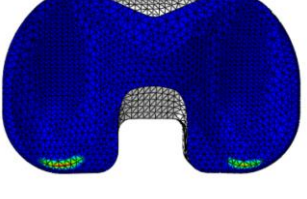
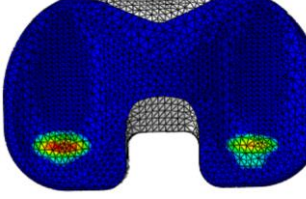
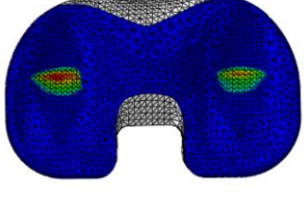
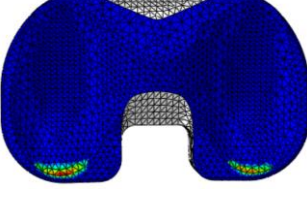
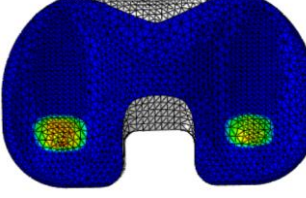
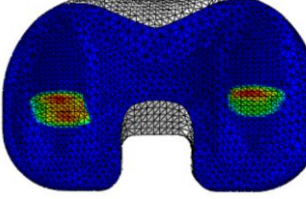
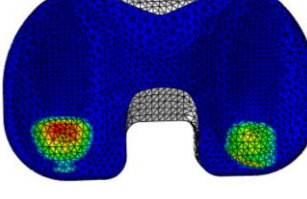
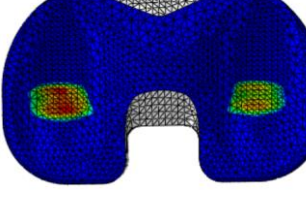
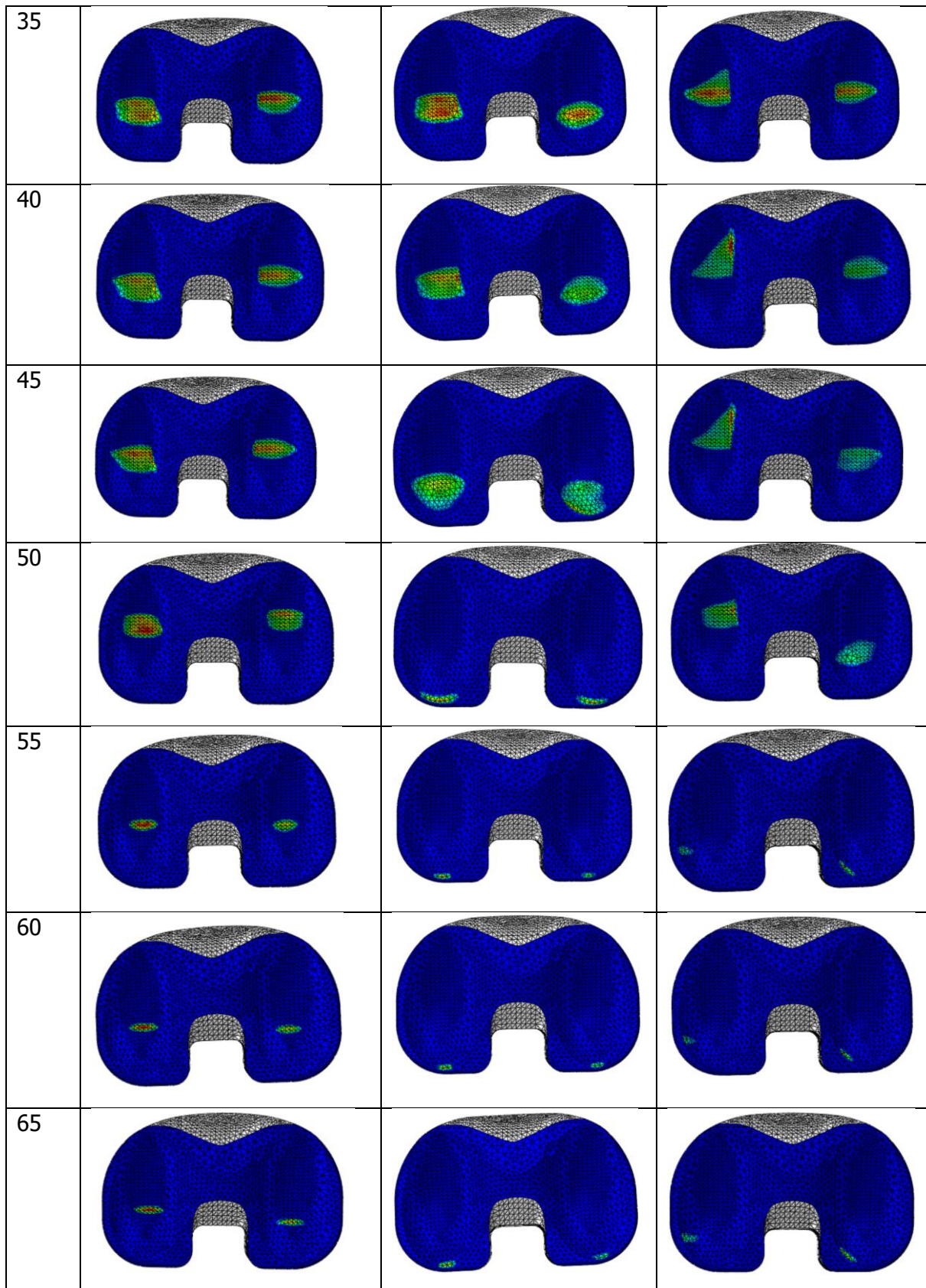


% Cycle	ISO 2004 displacement control	ISO 2014 displacement control	Leeds gait displacement control
0			
5			
10			
15			
20			
25			
30			



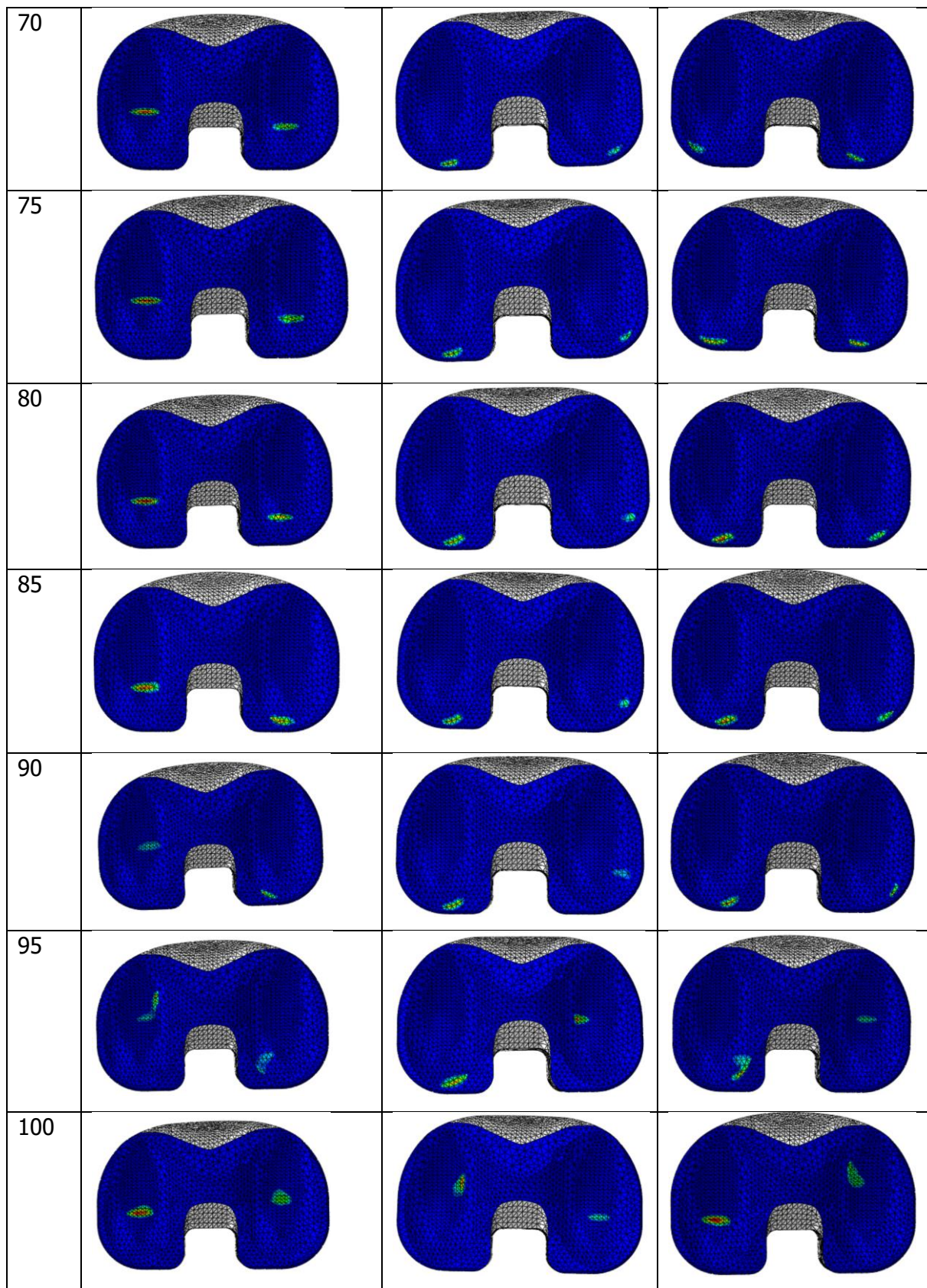
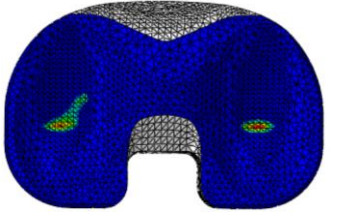
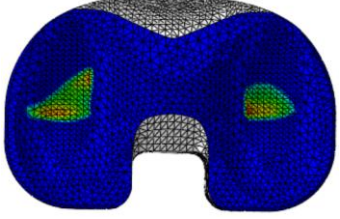
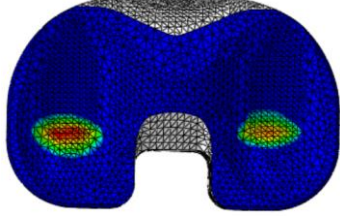
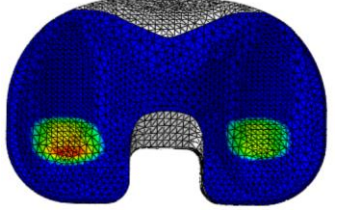
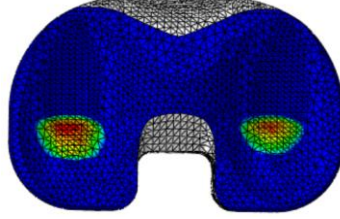
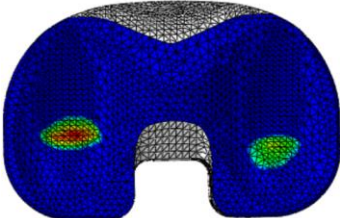
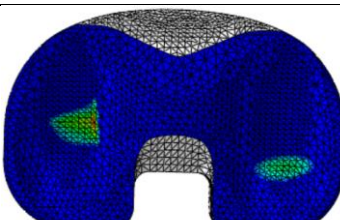
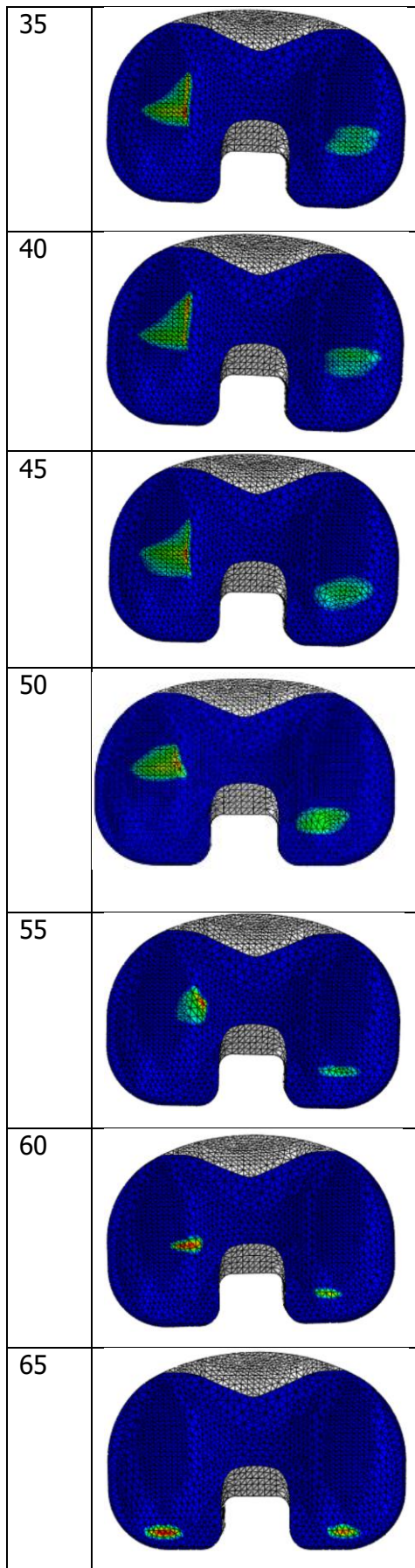


Figure 1: Computational contact scars at different points through the gait cycle using different displacement control test methods

% Cycle	ISO 2009 force control
0	
5	
10	
15	
20	
25	
30	



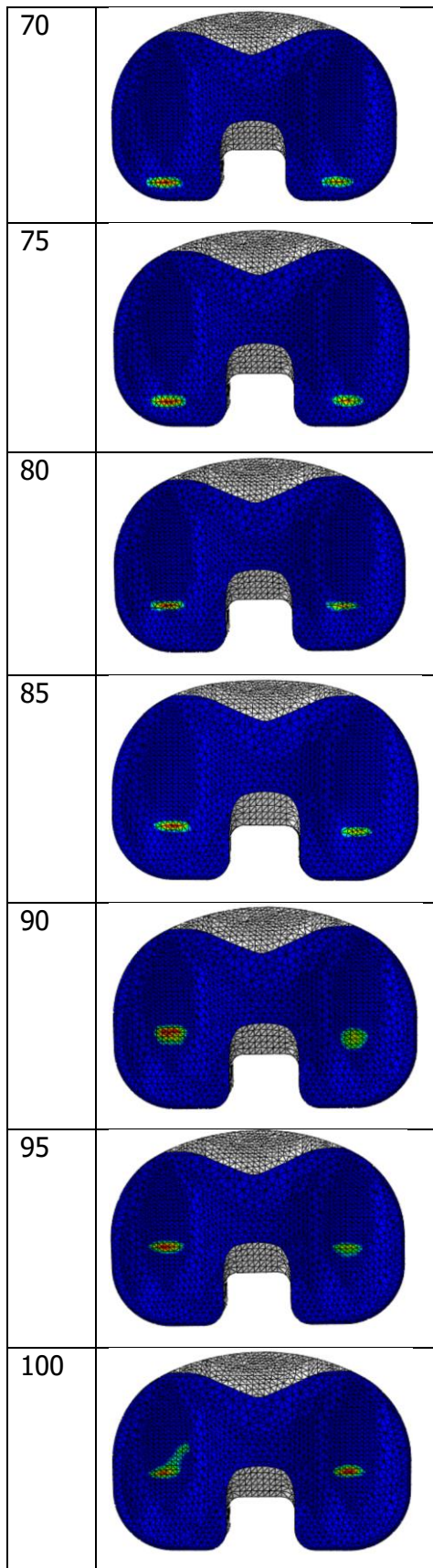


Figure 2: Computational contact scars at different points through the gait cycle using ISO 2009 force control test method